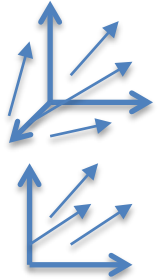


## Handout 2

Microsoft Mathematics: a software for 3D visualization – useful tool  
<http://www.microsoft.com/en-us/download/details.aspx?id=15702>

**Definition:** Vector is mathematical object that specify length/magnitude and direction. We denote a vector by putting a little over on the top, or sometime in books by using bold font.  $\vec{a}, \vec{u}, \vec{v}$  or  $\mathbf{a}, \mathbf{u}, \mathbf{v}$ . We write a vector as a list of numbers in angle brackets  $\langle x, y \rangle$  or  $\langle x, y, z \rangle$ .



Denote  $\vec{AB}$  a vector from point A to point B. One sketches  $\vec{AB}$  as a line segment with an arrow that point in the direction of the vector. However, the vector considered as a numerical quantity that doesn't represent the locations of A and B, but the location of point B relative to A as if A were the coordinate origin. Thus, vectors are position-less and therefore:

**Definition:** two vectors considered equivalent if their magnitude\length and direction is equal, regardless the position. Similarly  $\langle x_1, y_1, z_1 \rangle = \langle x_2, y_2, z_2 \rangle$   
 $\langle x_1, y_1 \rangle = \langle x_2, y_2 \rangle$  iff  $x_1 = x_2, y_1 = y_2, z_1 = z_2$ .

**Definition:** A vector from point  $A(x_1, y_1, z_1)$  ( $\vec{A}(x_1, y_1, z_1)$ ) to point  $B(x_2, y_2, z_2)$  ( $\vec{B}(x_2, y_2, z_2)$ ) is denoted as  $\vec{AB} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$  ( $\vec{AB} = \langle x_2 - x_1, y_2 - y_1 \rangle$ )

### Vector Arithmetic

Let  $\vec{a} = \langle a_1, a_2 \rangle, \vec{b} = \langle b_1, b_2 \rangle, \vec{c} = \langle c_1, c_2, c_3 \rangle, \vec{d} = \langle d_1, d_2, d_3 \rangle$  be a vectors and  $k$  a constant. In order to distinct vectors and numbers we will call  $k$  a **scalar**.

**Definition:** Defined the length or a magnitude of 2D, 3D vectors  $\vec{a}, \vec{c}$  respectively by  $\|\vec{a}\| = \sqrt{a_1^2 + a_2^2}$  and  $\|\vec{c}\| = \sqrt{c_1^2 + c_2^2 + c_3^2}$  respectively.

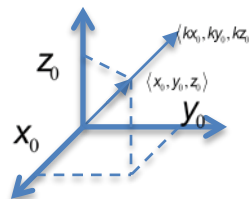
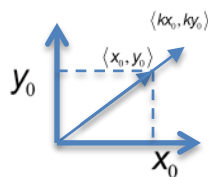
**Definition:** The **unit vector** is a vector with magnitude\length equal 1.

**Definition: Scalar Multiplication** defined as  $k\vec{a} = \langle ka_1, ka_2 \rangle$  and  $k\vec{c} = \langle kc_1, kc_2, kc_3 \rangle$ . If  $k < 0$  then the vector change direction. Note also that

$$\|k\vec{a}\| = \sqrt{k^2 a_1^2 + k^2 a_2^2} = |k| \sqrt{a_1^2 + a_2^2} = |k| \|\vec{a}\| \quad \text{and}$$

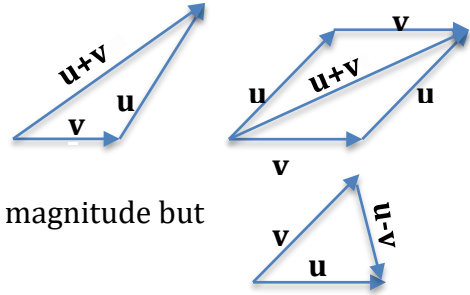
$$\|k\vec{c}\| = \sqrt{k^2 c_1^2 + k^2 c_2^2 + k^2 c_3^2} = |k| \sqrt{c_1^2 + c_2^2 + c_3^2} = |k| \|\vec{c}\|$$

Thus scalar multiplication scales (either stretch or squeeze) vector magnitude\length.



**Note:** Every vector  $\mathbf{u}$  can be converted into a unit vector by multiplying it by very special scalar equal to reciprocal of its magnitude:  $\left\| \frac{1}{\|\vec{u}\|} \vec{u} \right\| = \left| \frac{1}{\|\vec{u}\|} \right| \|\vec{u}\| = \frac{\|\vec{u}\|}{\|\vec{u}\|} = 1$ .

**Definitino: Vector Addition** defined as  $\vec{a} + \vec{b} = \langle a_1 + b_1, a_2 + b_2 \rangle$  and  $\vec{c} + \vec{d} = \langle c_1 + d_1, c_2 + d_2, c_3 + d_3 \rangle$ . The addition of vectors can be understood geometrically as as a Triangle Law or a Parallelogram Law, which are illustrated below.



**Definition: Vector Subtraction** defined by  $\vec{u} - \vec{v} = \vec{u} + (-\vec{v})$  where  $-\vec{v}$  is the vector with the same magnitude but opposite direction  $\vec{v}$ .

**Properties of vectors:**

1.  $\vec{a} + \vec{b} = \vec{b} + \vec{a}$
2.  $(\vec{a} + \vec{b}) + \vec{c} = \vec{a} + (\vec{b} + \vec{c})$
3.  $\vec{a} + \vec{0} = \vec{a}$
4.  $\vec{a} + (-\vec{a}) = \vec{0}$
5.  $k(\vec{a} + \vec{b}) = k\vec{a} + k\vec{b}$
6.  $(k + m)\vec{a} = k\vec{a} + m\vec{a}$
7.  $(km)\vec{a} = k(m\vec{a})$

### Standard basis (i-j-k notations)

We define 3 very important vectors, called a **Standard Basis**:

$\mathbf{i} = \langle 1, 0, 0 \rangle$ ;  $\mathbf{j} = \langle 0, 1, 0 \rangle$ ;  $\mathbf{k} = \langle 0, 0, 1 \rangle$  in 3D or equivalently  $\mathbf{i} = \langle 1, 0 \rangle$ ;  $\mathbf{j} = \langle 0, 1 \rangle$  in 2D.

**Theorem:** Every vector can be expressed as a sum of vectors of the standard basis as following

$$\langle a_1, a_2, a_3 \rangle = a_1 \langle 1, 0, 0 \rangle + a_2 \langle 0, 1, 0 \rangle + a_3 \langle 0, 0, 1 \rangle = a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k}$$

$$\langle a_1, a_2 \rangle = a_1 \langle 1, 0 \rangle + a_2 \langle 0, 1 \rangle = a_1 \mathbf{i} + a_2 \mathbf{j}$$